DVCon 2012

Design & Verification Conference & Exhibition

February 28 – March 1, 2012

A Practical Approach to Measuring and Improving the Functional Verification of Embedded Software

Stéphane Bouvier
STMicroelectronics

Nicolas Sauzède
STMicroelectronics

Florian Letombe
SpringSoft

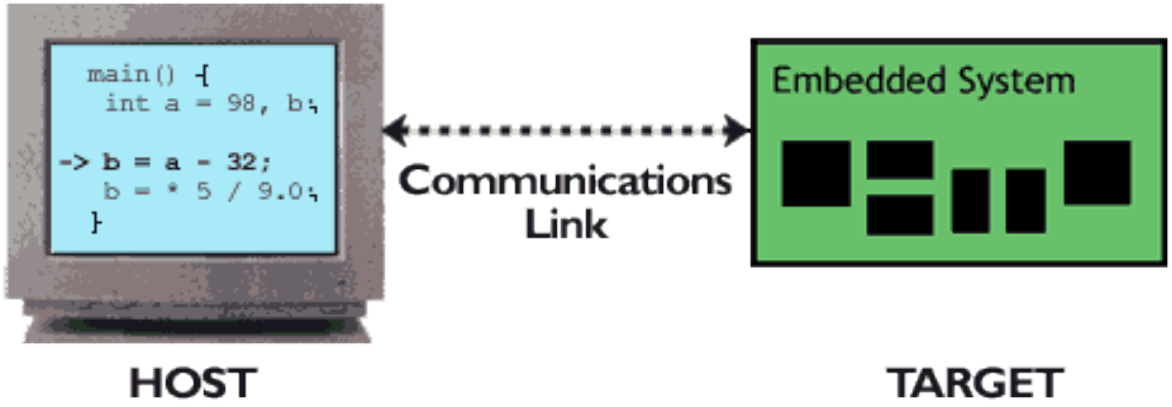
Julien Torrès
SpringSoft

Introduction

- Embedded systems development:
  - Systems tend to become more and more complex
  - Trend to have mixed hardware/software systems (RTL + firmware)
- Verification is difficult:
  - Are all scenarios covered?
  - Are all the specified functionalities checked?
  - This is even more difficult with mixed hardware/software systems
- But verification is important:
  - Bugs may be very costly

Embedded software development

- Host-target approach:
  - Develop on a host machine
  - Test on a target machine

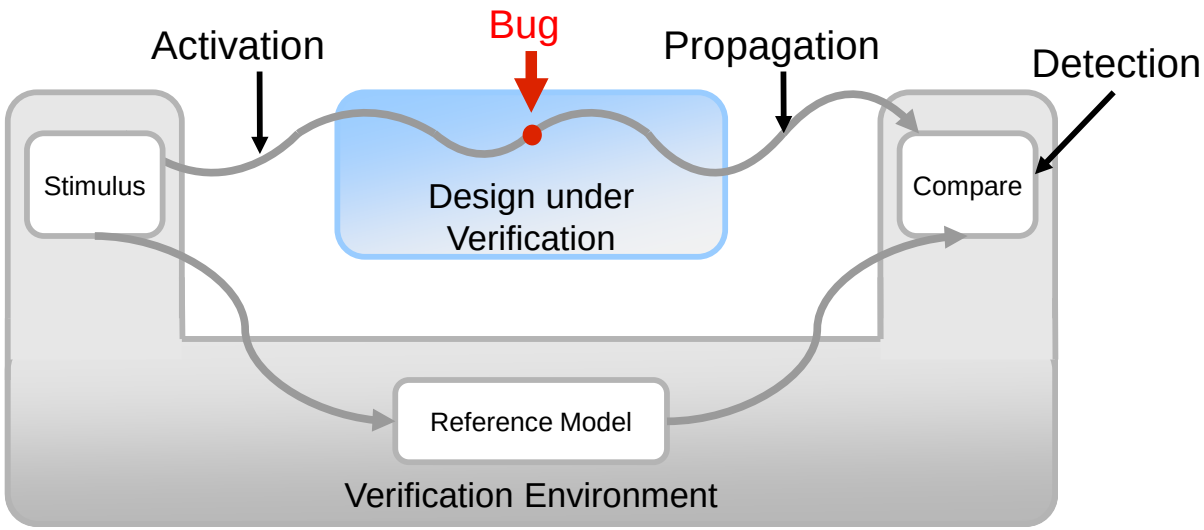


Embedded software debugging

- GNU Project debugger (gdb)
  - gdb running on the host machine
  - gdbserver running on the target machine
  - Communication through the gdb Remote Server Protocol (RSP)

Effective verification

It's all about activation, propagation, and detection

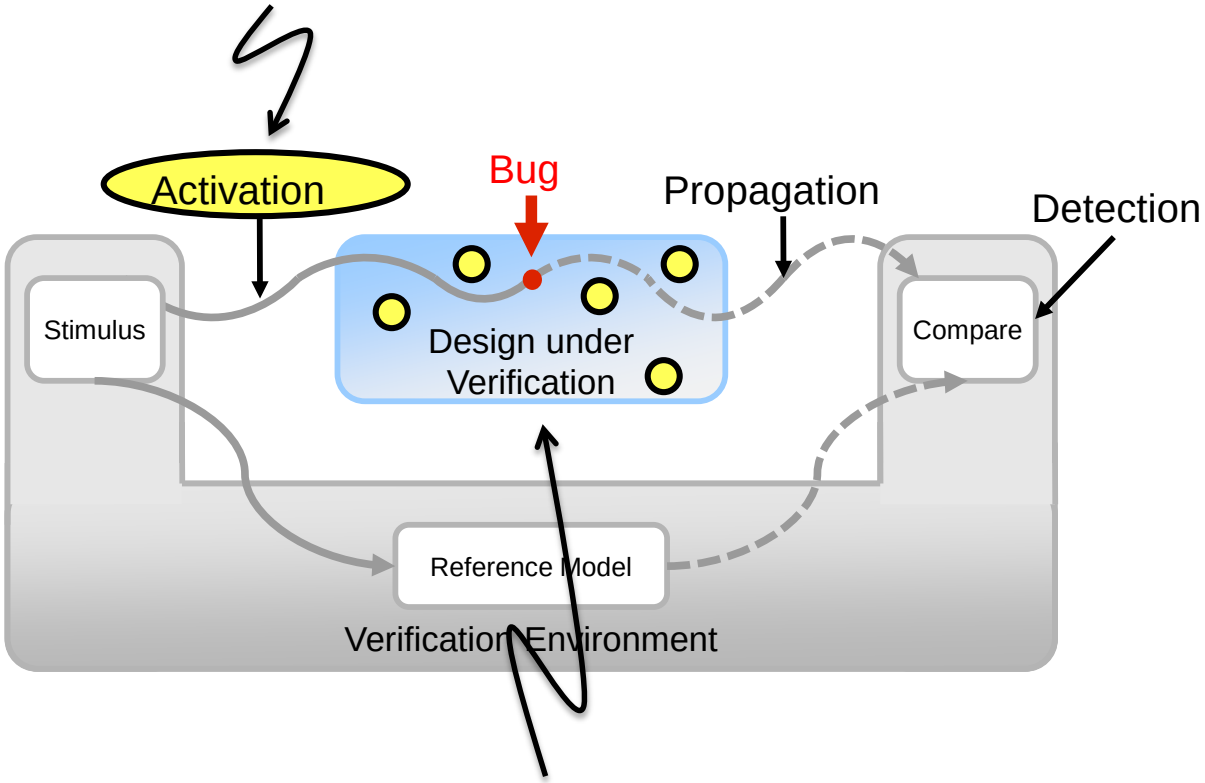


To detect a bug...

- The stimulus must **activate** the buggy logic
- An effect of the bug must **propagate** to an observation point
- The environment must **detect** the behavior difference due to the bug

Existing tools are insufficient

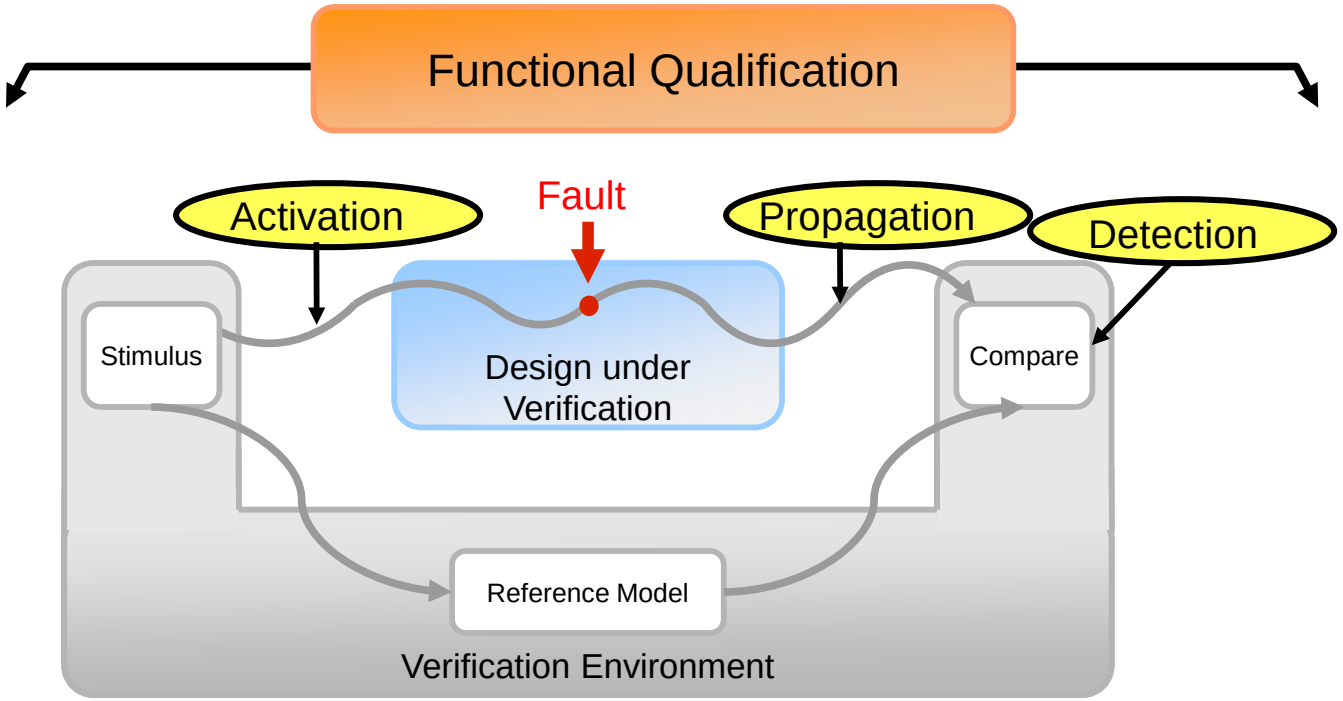
Code coverage *measures activation, but says nothing about propagation or detection*



Functional coverage *checks "important" functional points, but is subjective and incomplete*

Functional qualification

- Based on mutation analysis
- Inserts “artificial bugs” (mutations) called faults into the design
- Measures the ability of the verification environment to **activate**, **propagate**, and **detect** the faults
- “Qualification” of the verification environment against many inserted faults provides objective measure of overall quality and identifies holes and weaknesses



How functional qualification works

- Modifies code to insert faults

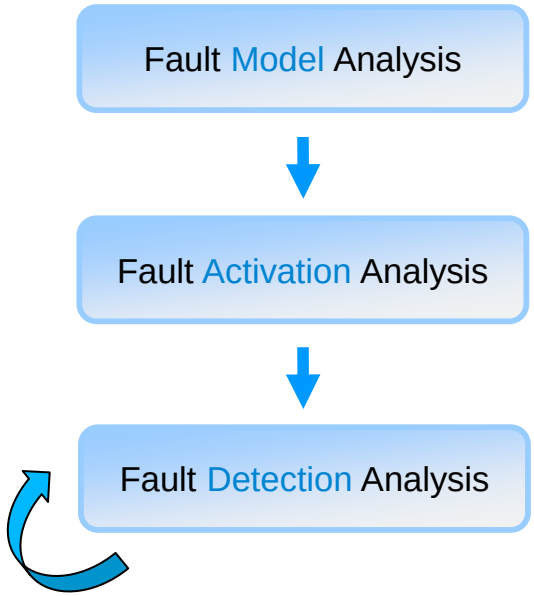
```
a = b | c   →  a = b & c   // change operator

if (a)      →  if (TRUE)   // force execution of "if" branch
  f1();           f1();
else              else
  f2();             f2();
```

- Simulates the broken code with the test suite
  - Does at least one test fail? *Great!*
    - The environment is robust enough to detect that the code is broken
  - Do all tests pass? *Help!*
    - You now have two versions of the code, both of which are compliant with the verification environment
    - This means that the environment could miss a real bug

Certitude: a functional qualification tool

- Certitude is a functional qualification tool developed by SpringSoft
- Process and flow:



Analyze the design (static) to determine the possible faults

- Write instrumented code

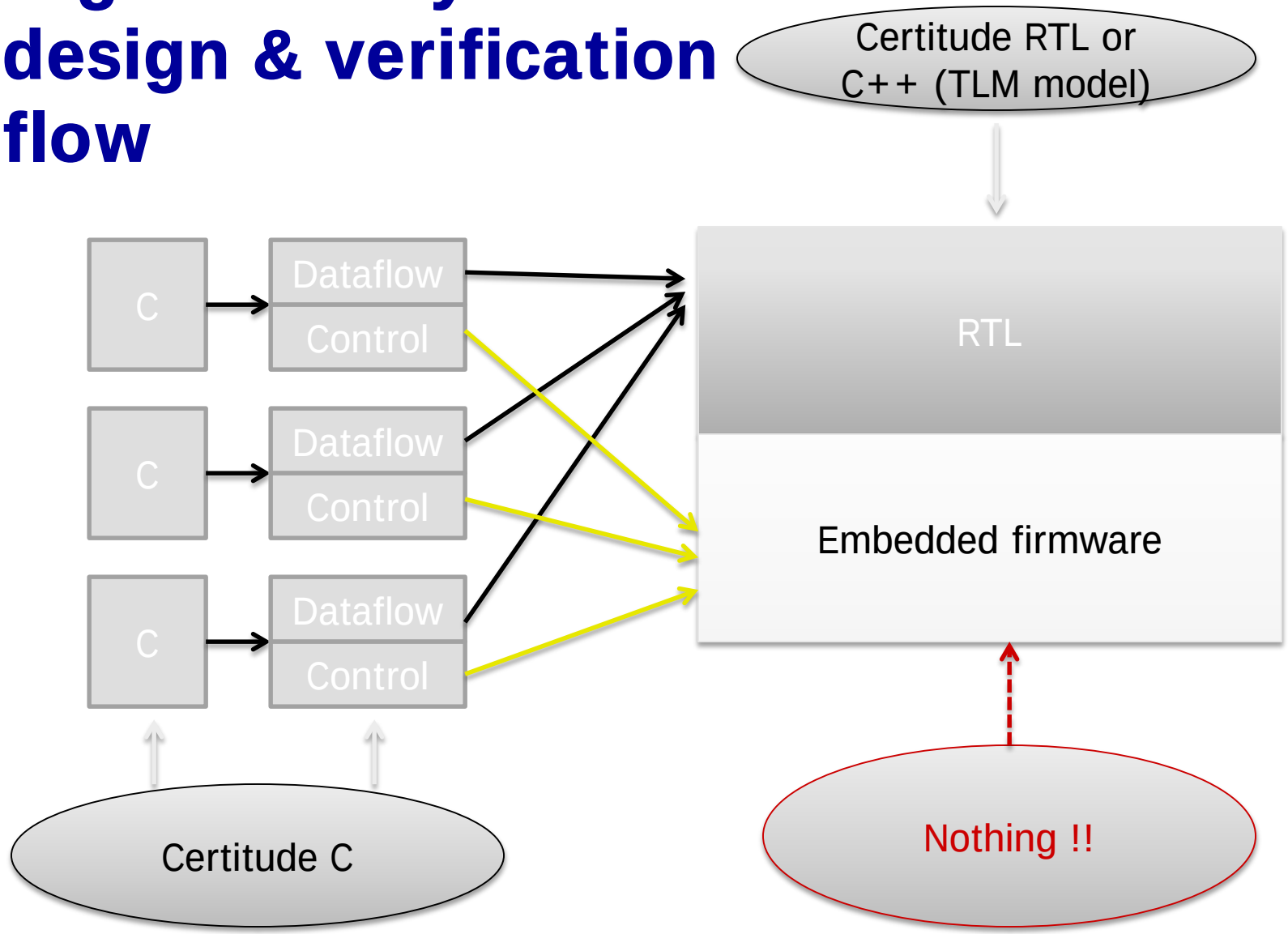
Analyze the verification environment by simulating tests once

Measure the ability to detect bugs by injecting faults and simulating

- ID non-detected faults
- Report details to direct fix

Fix and iterate as problems are found

High Level Synthesis design & verification flow

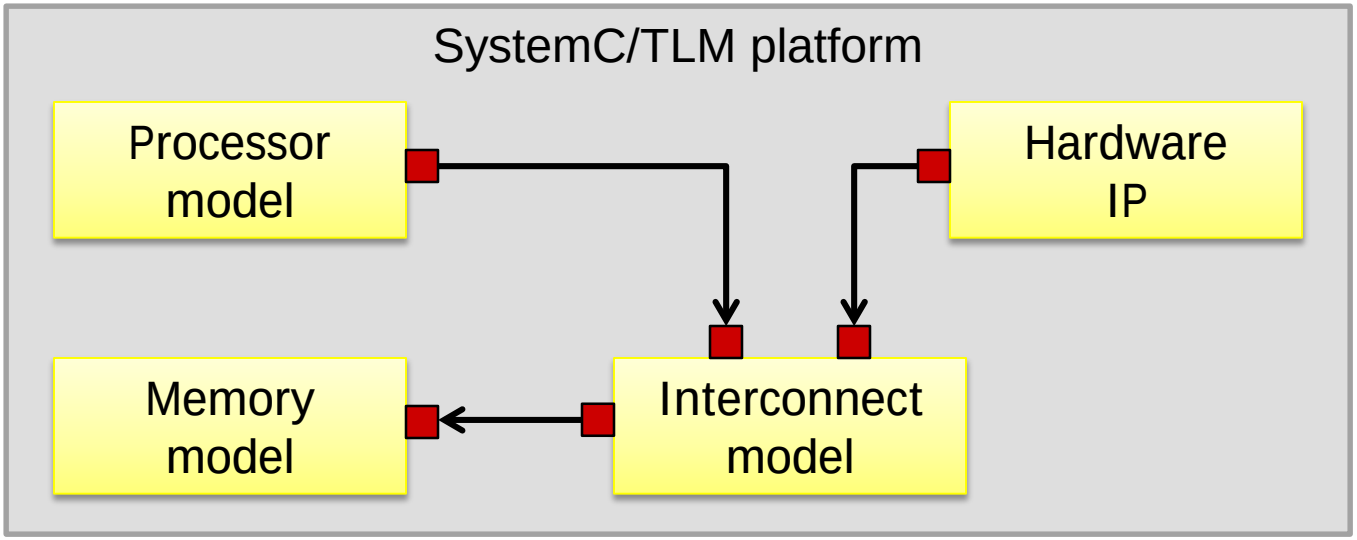


Certitude on embedded software issues

- Certitude is not usable on embedded software in its original version
- Communication issues:
  - Certitude uses control files to:
    - Inject faults
    - Monitor the simulation
    - Get the results
  - But: no file system is available on the embedded platform
- Certitude needs to be extended to support embedded software

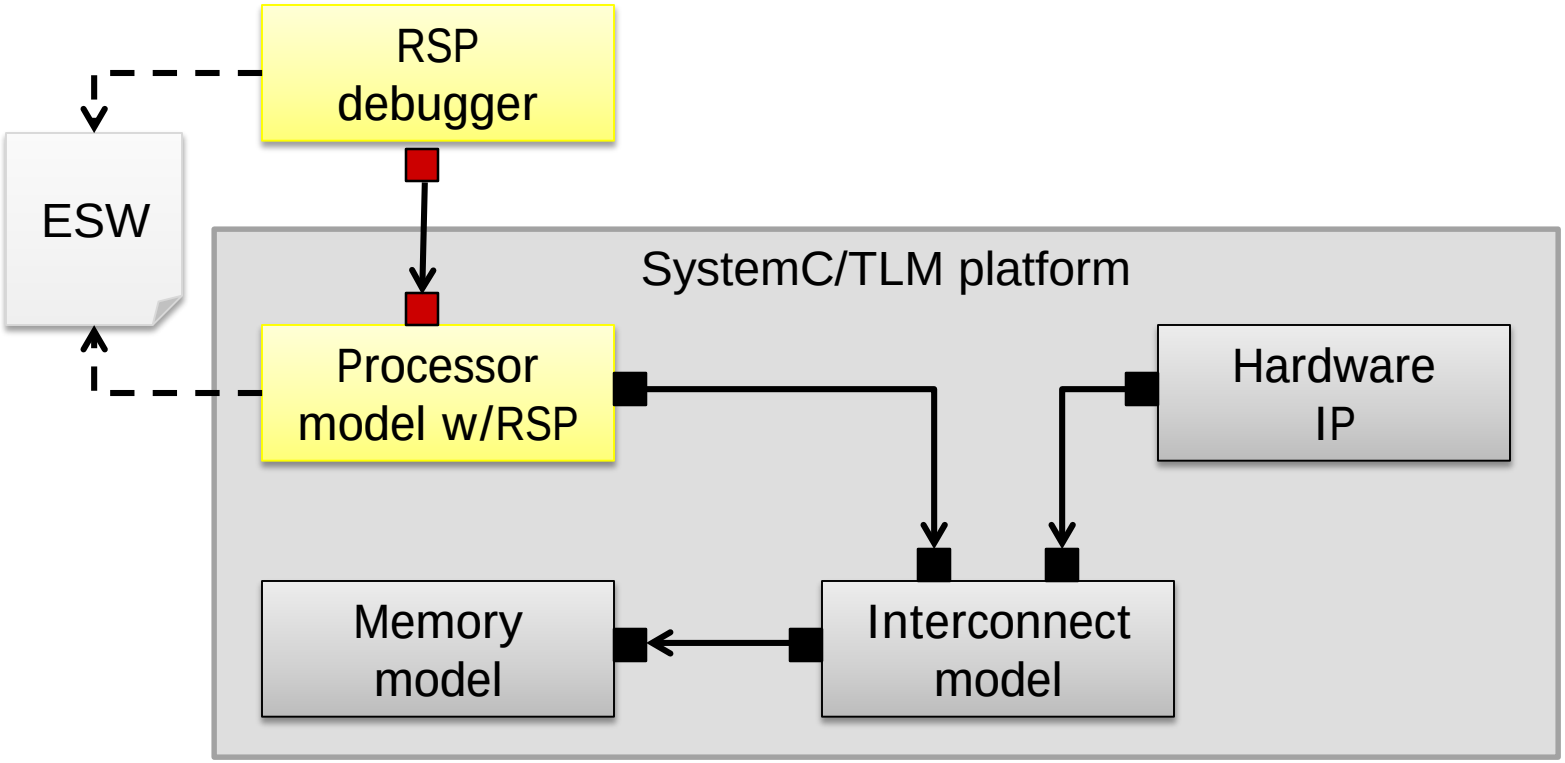
RSP enabled TLM platform (1/2)

- Transaction Level Modeling virtual platform:
  - Allows pre-silicon embedded software development
  - Accurate enough to allow software execution
  - Register-accurate, bit-accurate, loosely-timed
  - Industry standards : SystemC, TLM-2 (IEEE 1666)



RSP enabled TLM platform (2/2)

- Some TLM Processor models provide Remote Server Protocol (RSP) debug access
- Embedded software (ESW) can be debugged from outside



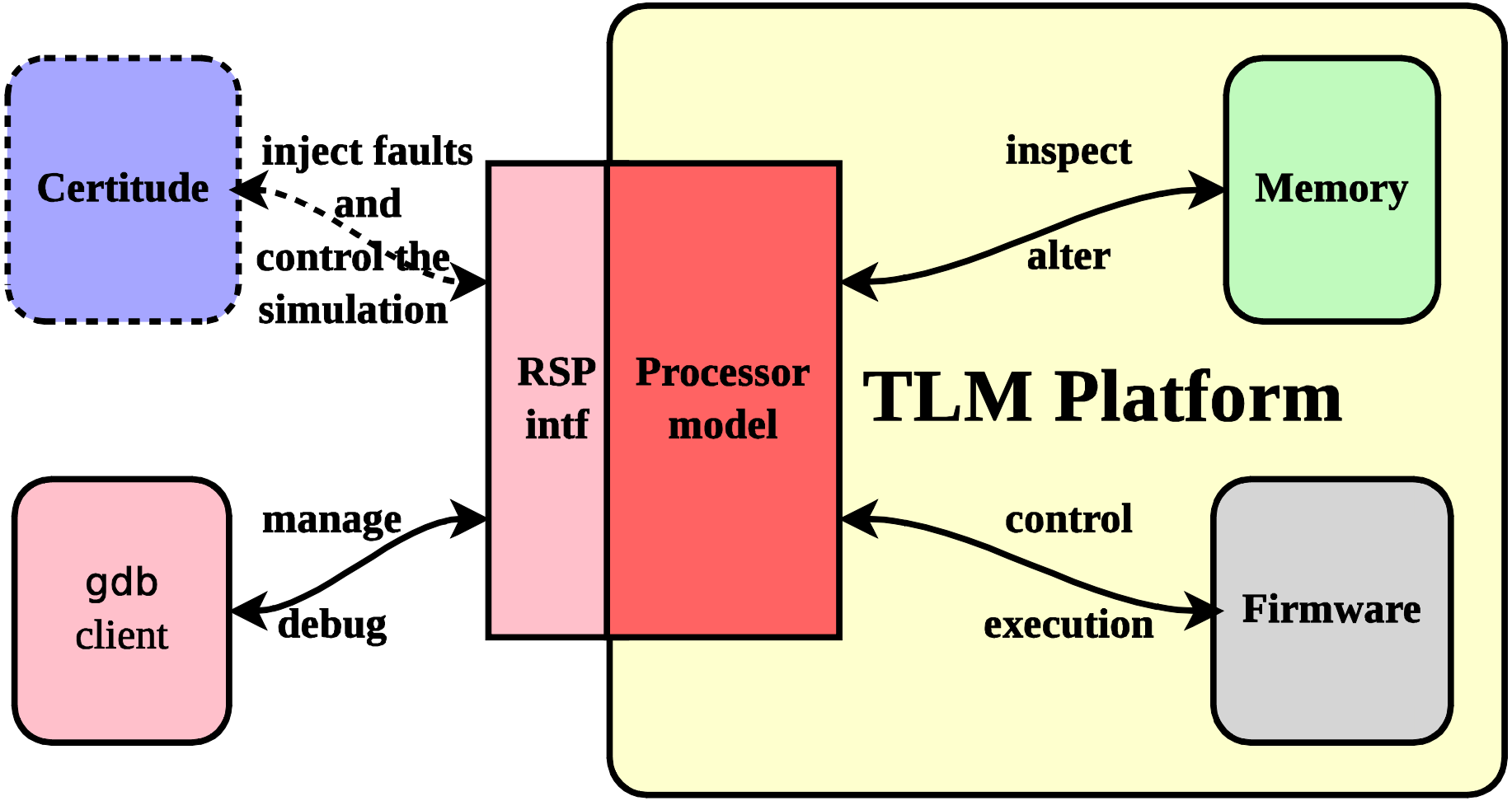
Using Certitude on embedded software (1/2)

- Certitude has been extended to solve the communication issues
- The platform supports the gdb RSP

  → The Certitude control files have been replaced by the RSP

  → Certitude behaves as a standard gdb client

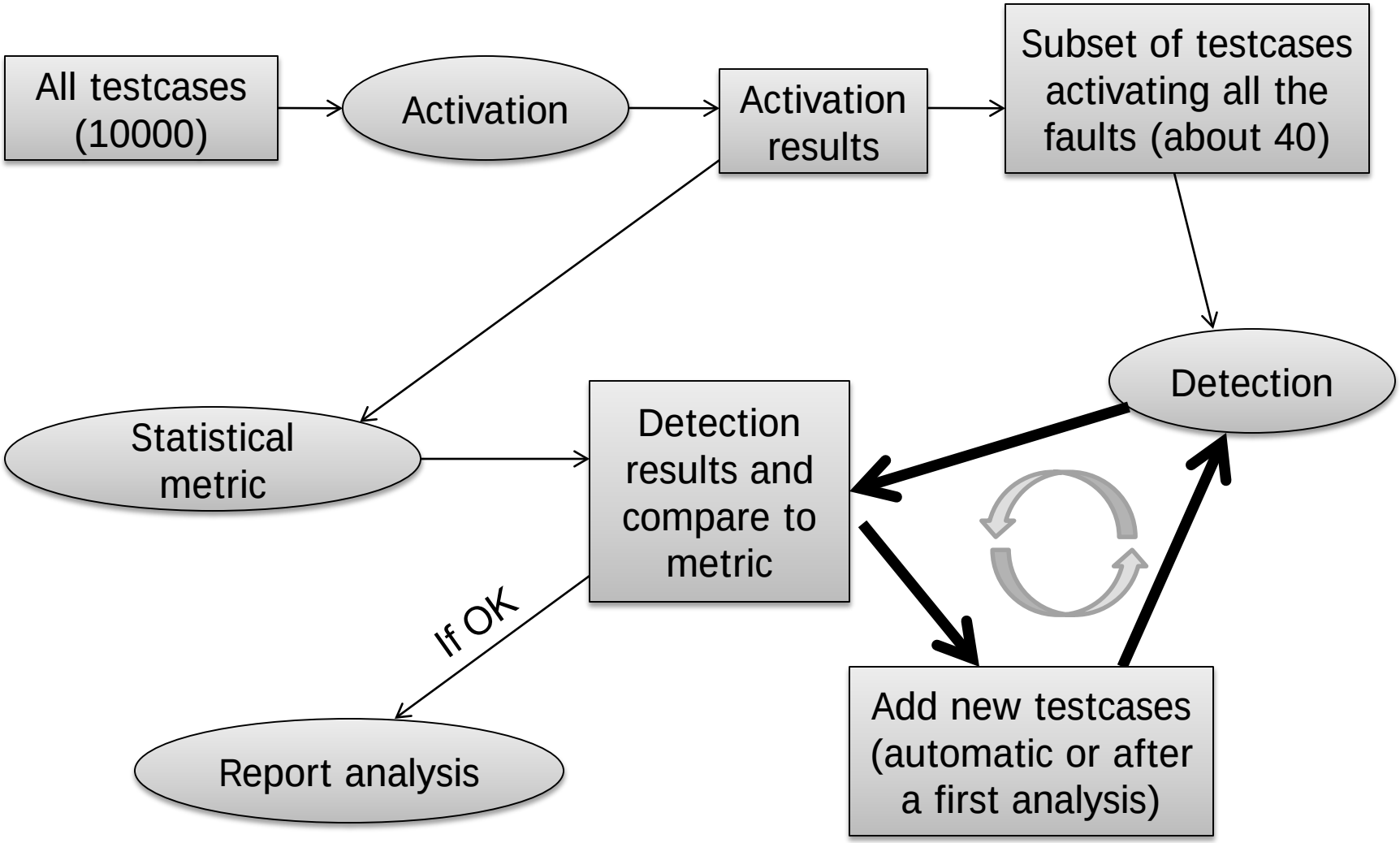
Using Certitude on embedded software (2/2)



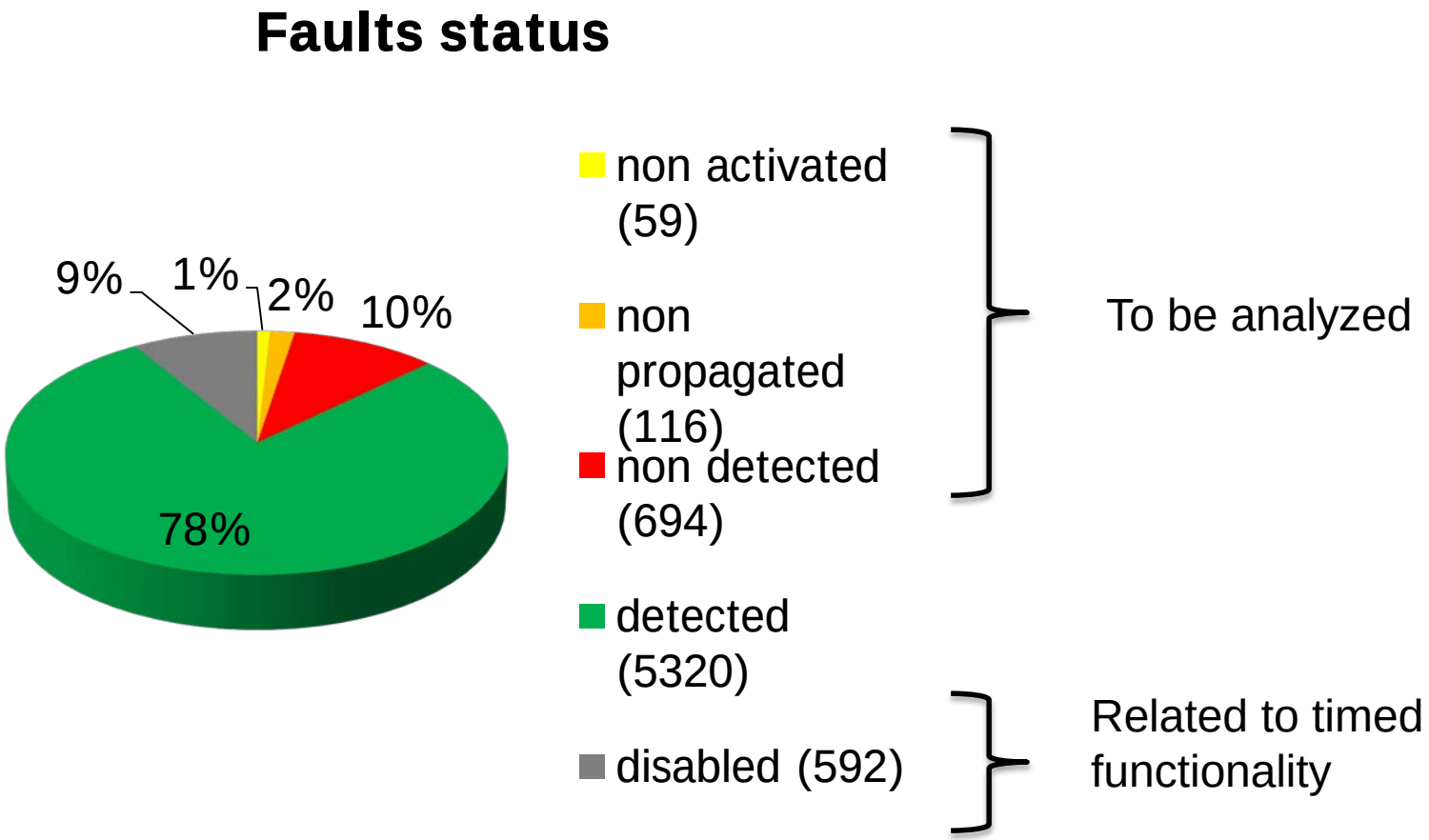
Use case: embedded firmware qualification

- DUV is a High Quality Video Display IP
- Embedded firmware mainly implements the control part of the DUV that was formerly done in RTL
- The data flow remains in RTL
- The firmware consists of:
  - 27 files
  - 14,000 lines of C
  - 46.7 kbytes in program memory
  - 6781 faults injected by Certitude

Methodology



Results


Faults status
9%
1%
2%
10%
78%
non activated (59)
non propagated (116)
non detected (694)
detected (5320)
disabled (592)
To be analyzed
Related to timed functionality

Results analysis

- Dead code found: code that cannot be activated or is out of the specification

  -> Save 2% of room in program memory (size limited)

- Missing tests: code that can be activated and that should be activated

  -> Add new tests to cover these functions

  - 4 new tests after activation

    -> find a corner case bug

  - 6 new tests after detection

Conclusion

- Certitude already validated on RTL and C standalone
- Certitude adapted for embedded software testing environments
- Experiments on High Quality Video Display IP:
  - Removed dead code
  - Added missing tests
  - Found a design bug and avoided respin